



Schweizerische Eidgenossenschaft  
Confédération suisse  
Confederazione Svizzera  
Confederaziun svizra

Eidgenössisches Departement für  
Wirtschaft, Bildung und Forschung WBF

**Agroscope**

# Spray drones in Switzerland



Image: S. Rüttimann

Thomas Anken, Agroscope Tänikon, 8356 Ettenhausen, [thomas.anken@agroscope.admin.ch](mailto:thomas.anken@agroscope.admin.ch)

# The Swiss legal approach

- For spray drones a «National standard scenario» has been developed <https://www.bazl.admin.ch/bazl/en/home/drohnen/specific/sts/ch-sts.html>
- drone type must be authorised by Agroscope for «ground application» and each drone passes a sprayer test
- drone operating company needs a «Specific Operations Risk Assessment» (SORA) approved by the Federal Office of Civil Aviation
- After 2025: Spray drones need an authorisation of the Federal Office of Civil Aviation based on SORA or EU-PDRA, according to (EU) 2019/947
  - an adaptation of the PDRA S-01 for spray applications is under work
- Today about 100 spray drones are in use in Switzerland

# Homologation of spray drones

- each drone type (1 machine) needs to be homologated by Agroscope
- each single drone passes a sprayer tests all 3 years (like other sprayers)

## Testing criterias for the homologation

- spray system fulfils principles of ISO 16122
- transversal distribution of spray liquid:  
coefficient of variation < 15 %
- accuracy of automated flight route: +/- 50 cm
- max. lateral windspeed (check for drift reduction)

Distance from drone	Meters above soil	wind speed m/s
<b>10 m</b>	1 m	5 m/s
	2 m	3 m/s
<b>20 m</b>	1 m	3 m/s
	2 m	2 m/s

Details see:

<https://www.bazl.admin.ch/bazl/en/home/drohnen/specific/sts/ch-sts.html>

«Spray drones: Testing and approvals of sprayers»





# Control of spray system (ISO 16122)

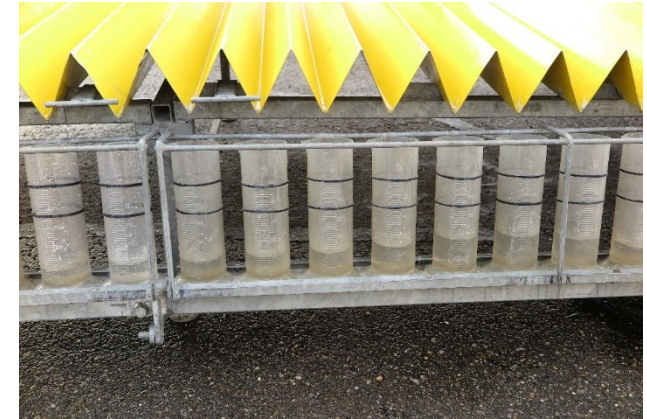


## Standard checks of the spray system like:

filters available, dripping of nozzles after stop of spraying, nozzle flow, flow or pressure indication, leakages, weights...



# Transversal distribution of spray liquid



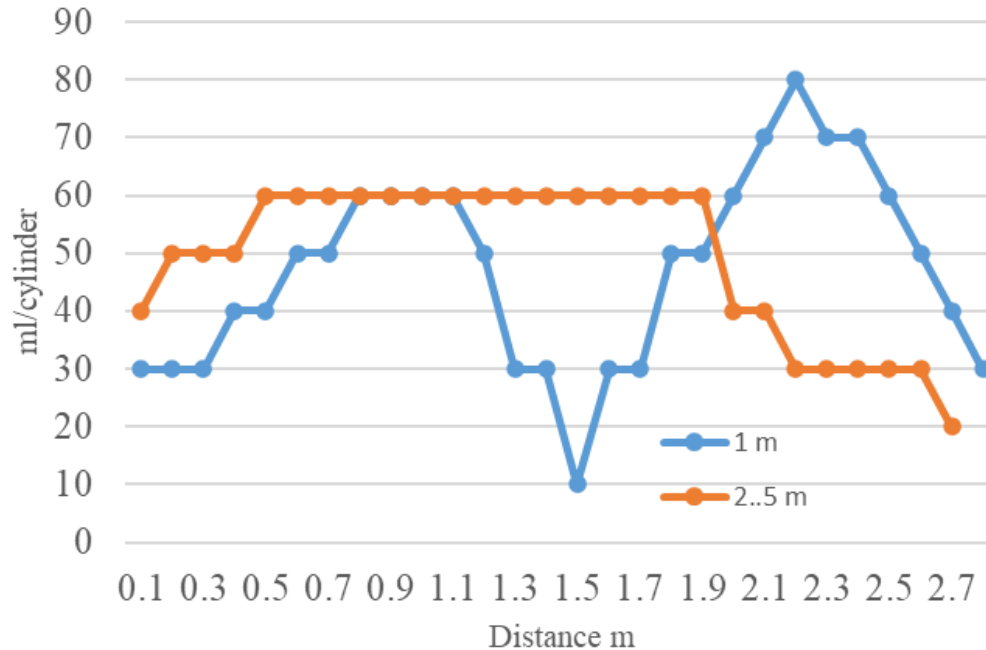
Patternator (6 m x 3 m, same principle as the ones for field sprayers)

- drone is hovering at the same place over the patternator
- lateral wind is strongly influencing the distribution
- flying height 2.5 m



# Flying height influences distribution

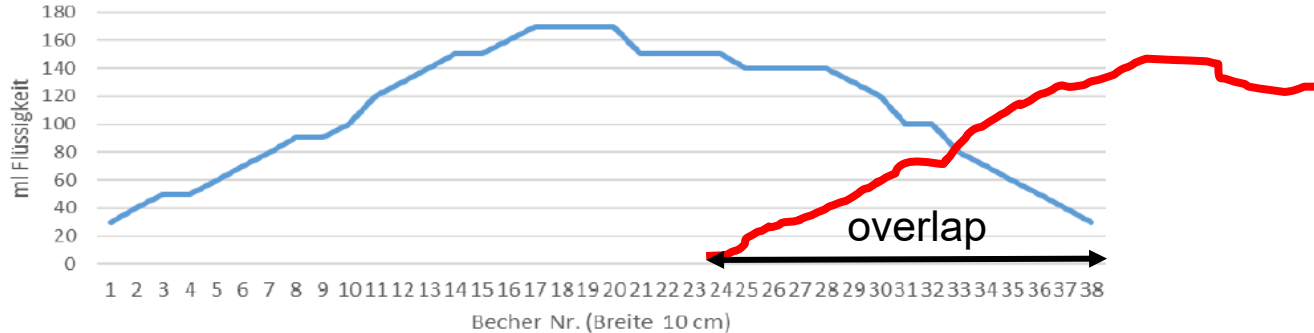
transversal distribution at 1 and 2.5 m flying height



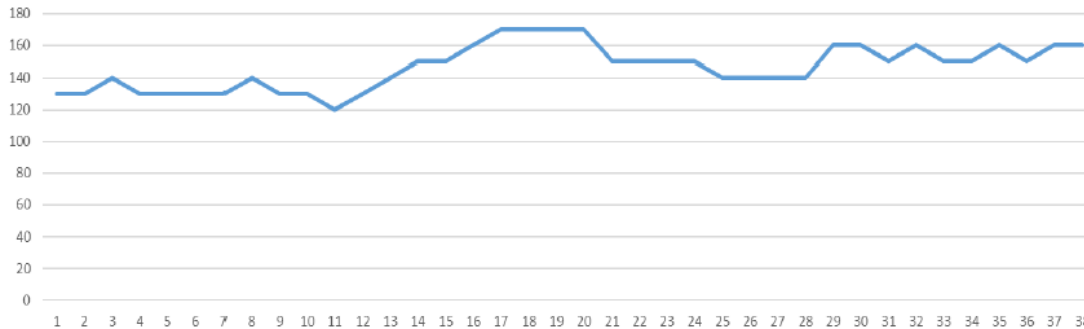
- Flying height of 1 m and less is not delivering a good distribution
  - 2.5 – 3 m delivers a much better distribution
- less influence of the single propellers, more homogeneous air flow

# Overlap of two spray swathes is calculated

no overlap, working width of 3.8 m – coefficient of variation 48 %



overlap 1 m on both sides, working width of 2.8 m – coeff. of variation 9.4 %



- During the sprayer tests we calculate the optimal overlap to reach the lowest coefficient of variation
- working width are lower than the indications of DJI
- today most drones achieve a coefficient of variation < 15 %





# Comparison of 3 methods to measure transversal distribution



- patternator
- tracer and photometric analysis
- water sensitive paper: treated surface determined by computer vision

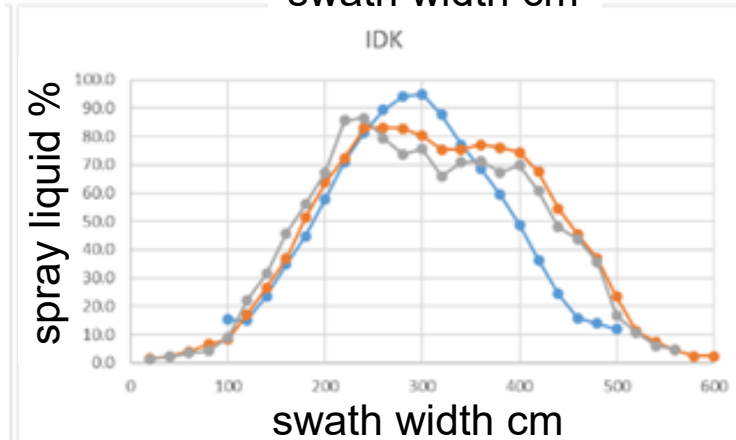
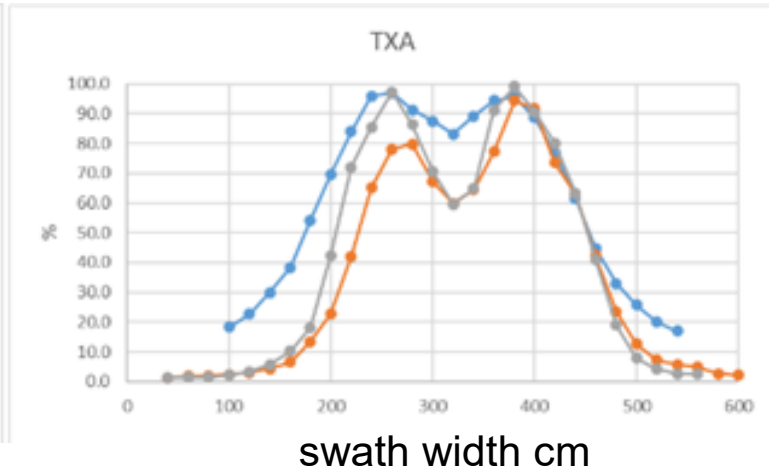
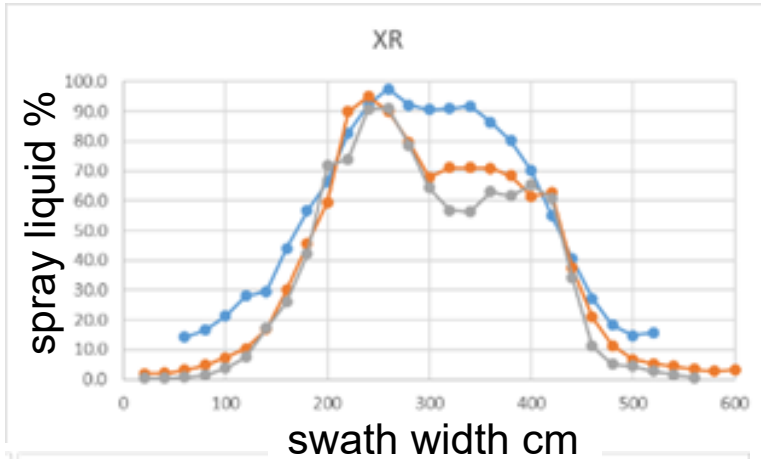
executed in collaboration with Syngenta



- yellow water sensitive paper
- white filter paper for tracer



# Transversal distribution of different nozzles and measuring methods



patternator

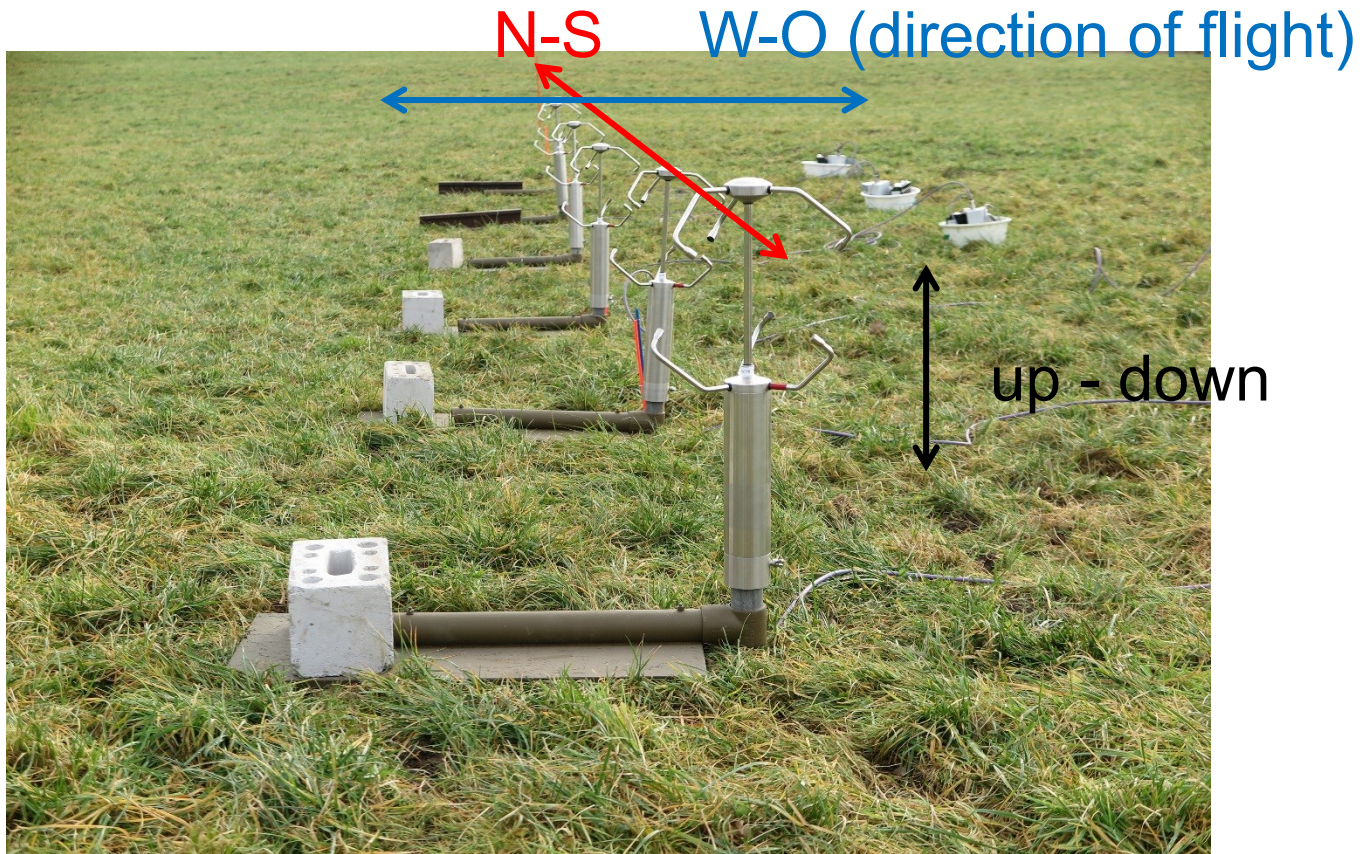
tracer

water sensitive paper

- Teejet XR (flat fan) & TXA (hollow cone), Lechler IDK (flat fan air injection) (Drone DJI T16)
- «water goes where the wind blows» → no significant influence of nozzles
- no significant differences between different methods

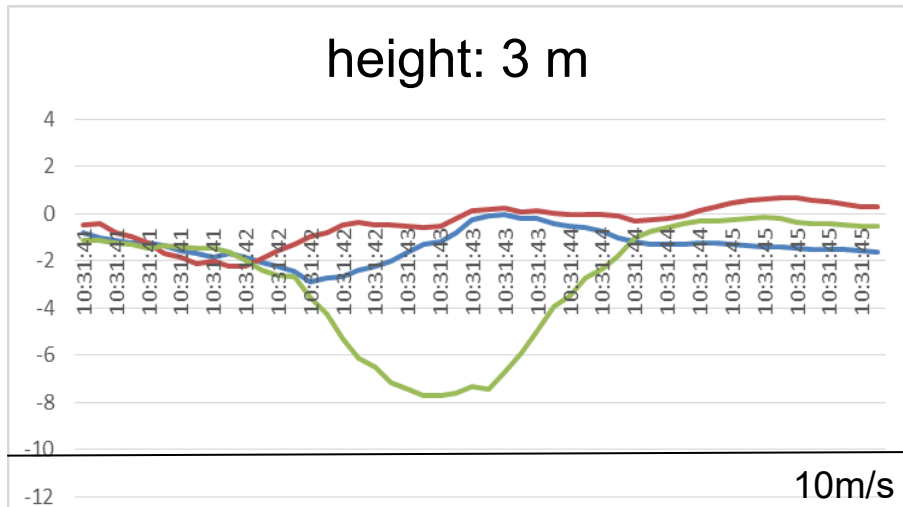
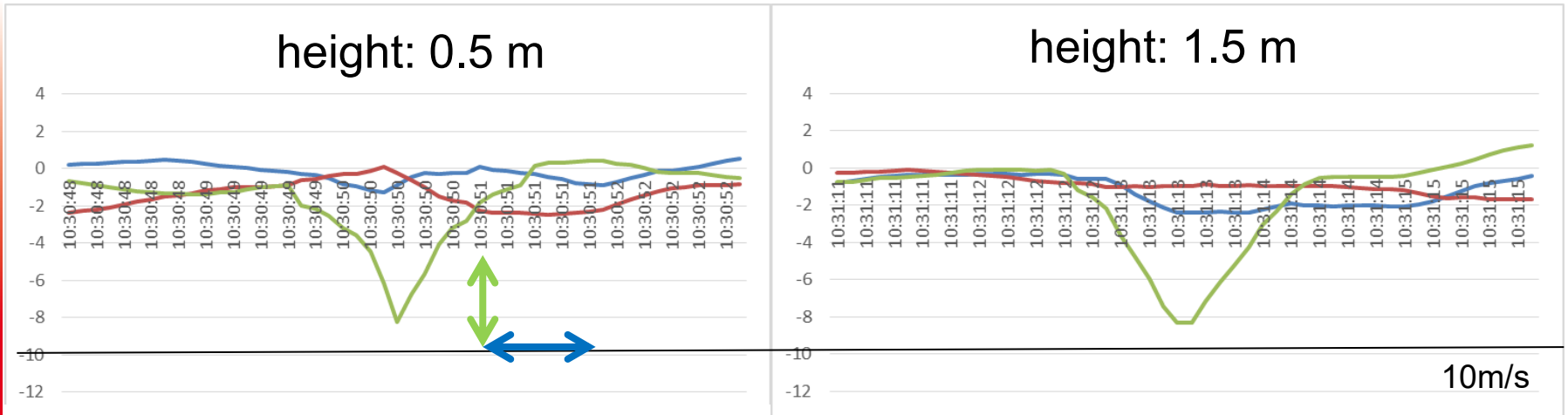


# Measuring wind speed



Each sensor is measuring wind speed in three directions  
west-east; north-south; up-down (10 Hz)

# Windspeeds directly below a drone of 25 kg

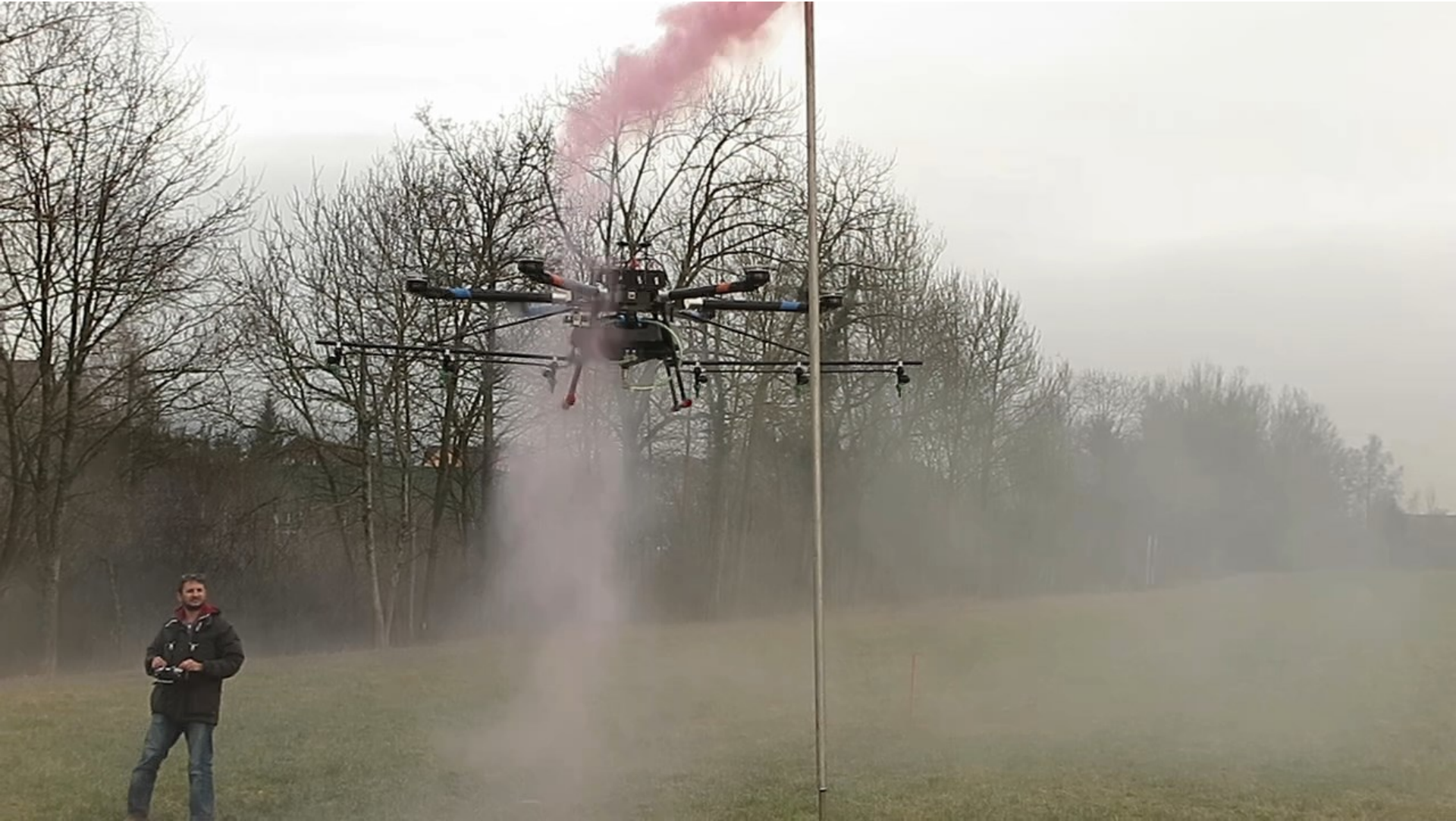


- low lateral windspeeds, vertical speeds up to 8 m/s
- ideal for reducing drift





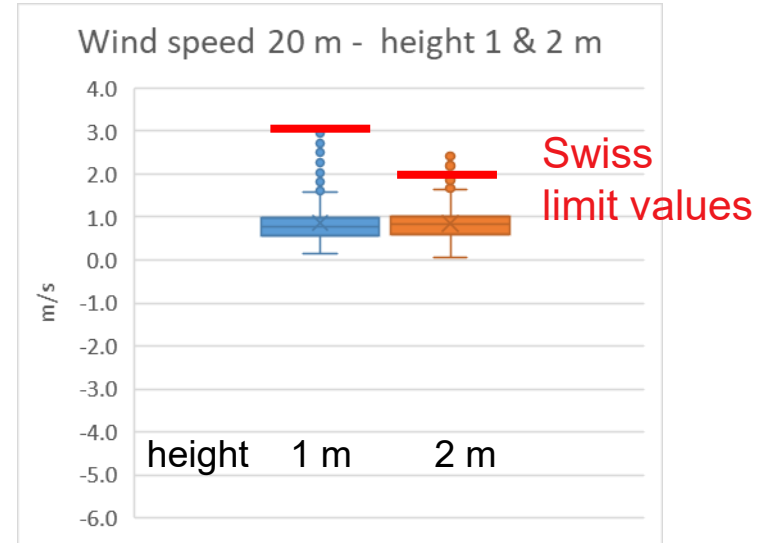
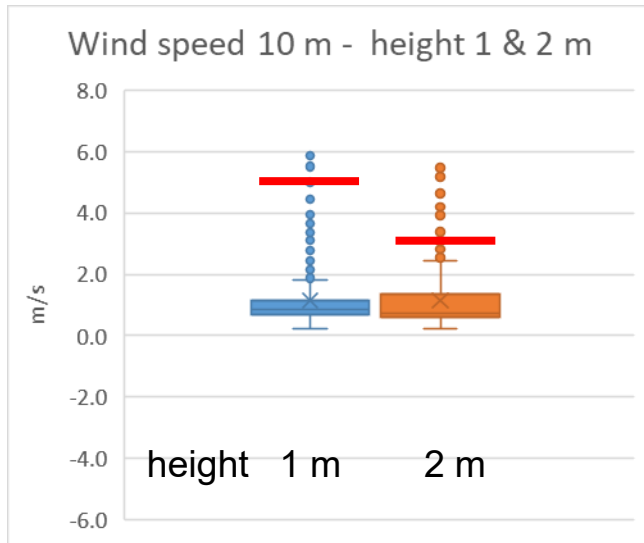
# Visualisation using smoke



**Spray drones in Switzerland**

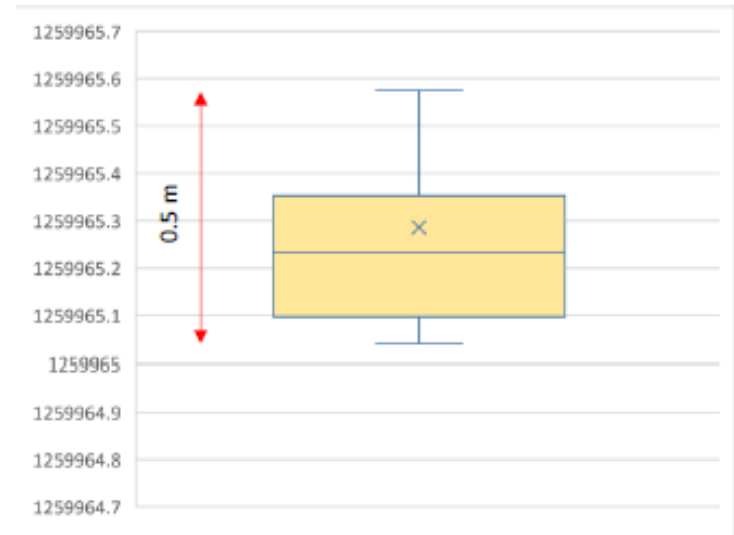
Thomas Anken | Agroscope , Tänikon 1, CH-8356 Ettenhausen

# Wind speeds of DJI T30, distance 10 & 20 m



→ heavier drones like DJI T30 lead to higher wind speeds, slowly approaching the limit values

# Accuracy of flight route



drone is flying along a defined route  
simulating a field (3 swathes)

drone is carrying an additional  
RTK-GNSS data logger to measure  
the deviation of the defined route

achieved accuracies in general:

- values are within 0.5 m
- 50 % of values +/- 10 cm

RTK logger



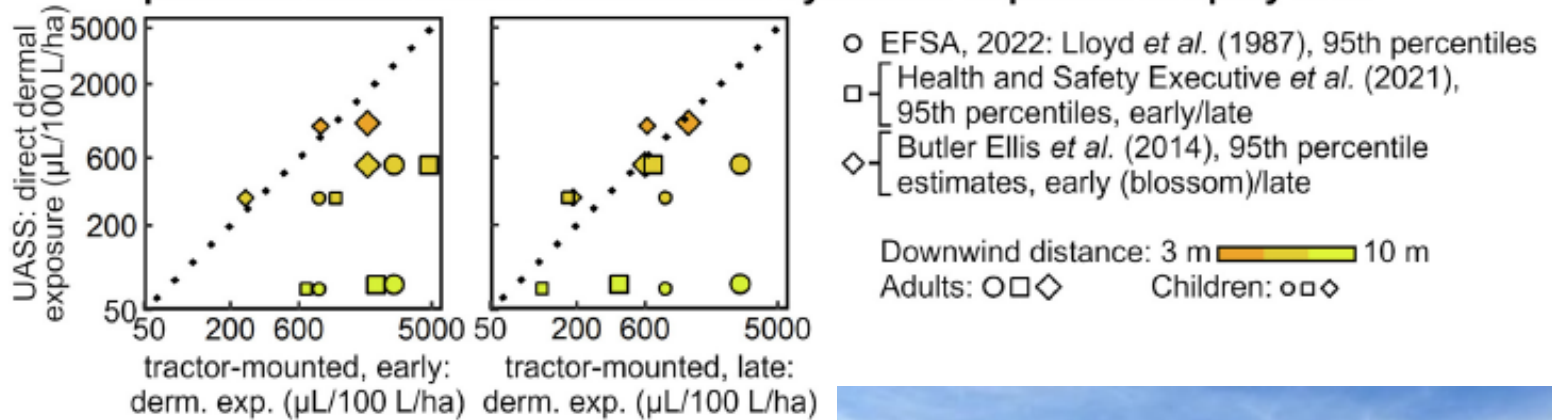




# Drift and bystander measurements

→ spray drift of drones has been quantified by means of bystanders and tracer measurements

## B tractor-mounted spraying equipment vs. UASS: potential direct dermal resident and bystander exposure to spray drift



(Dubuis *et al.* 2023)

→ spray drift of drones is lower than standard tractor mounted blast sprayers

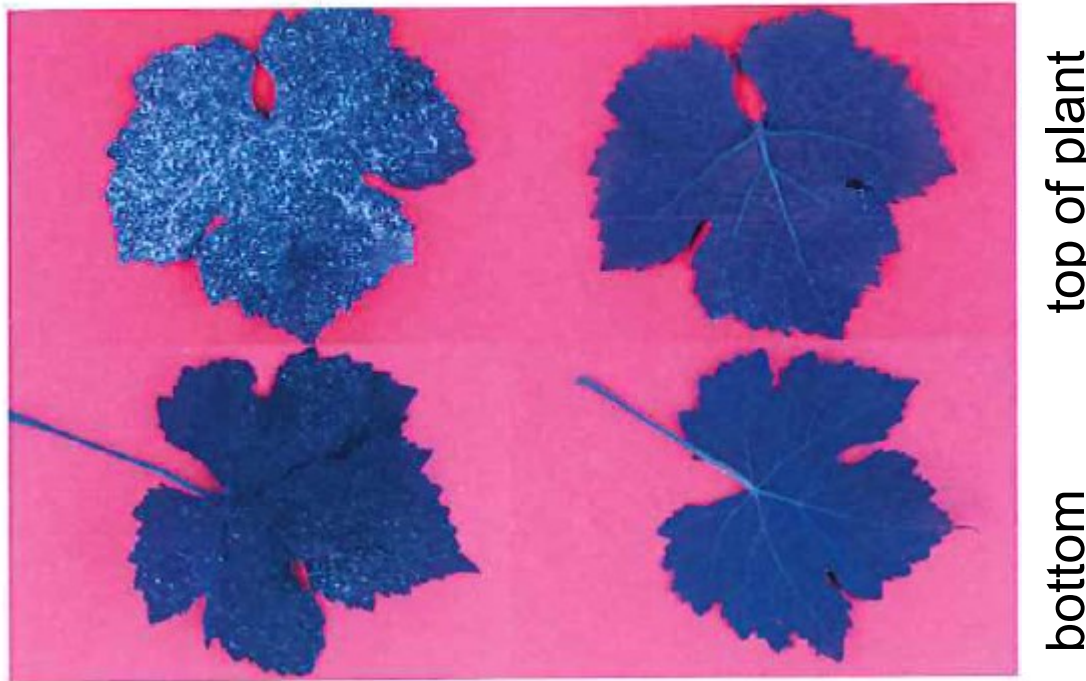




# Efficacy of the treatment on vine

leave upside

leave underside

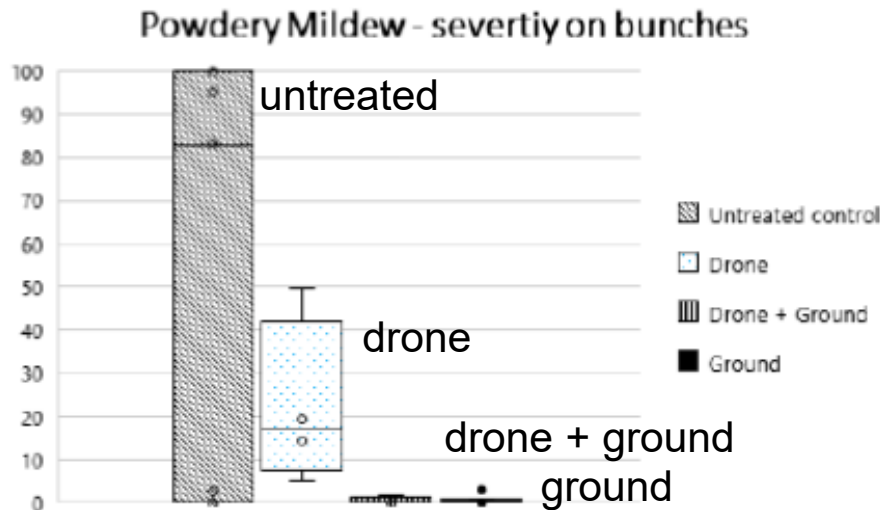
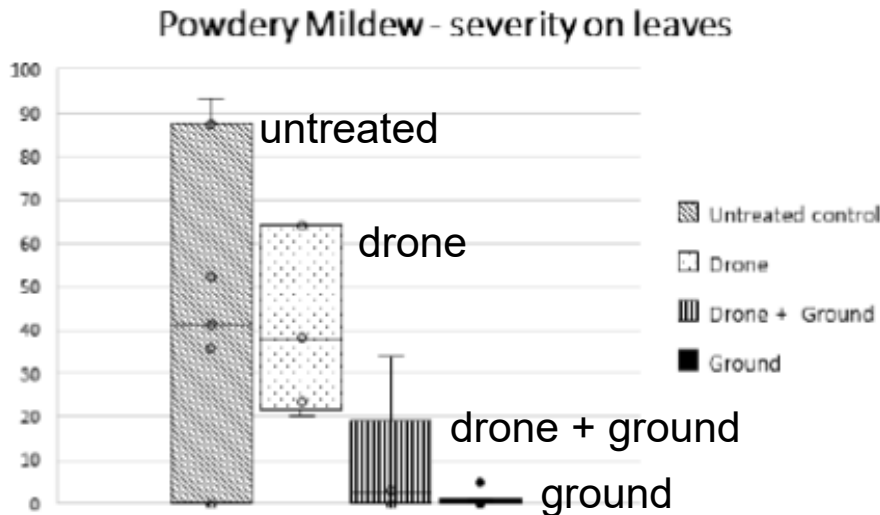


- downsides of leaves and bottom of plants as bunches are not well treated

(Dubuis & Jaquero 2021)



# Efficacy of the treatments on vine



**Average disease pressure:**  
combination with at least one complementary spray from the ground allows reaching reasonable levels of control

(Dubuis & Jaquero 2022)





# Conclusions

- drones found their place in vineyards with steep slopes
- homologation and sprayer tests work well since 5 years
- many positive echoes as hard, exposed work with knapsack sprayers can be replaced
- drones are replacing helicopters but not tractors
- limits in efficacy have to be well respected



**Spray drones in Switzerland**

Thomas Anken | Agroscope , Tänikon 1, CH-8356 Ettenhausen